Strongly minimal theories with computable models

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July 10, 2013

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# Motivation

In computable model theory, there is work on the algorithmic complexity of the models of a given elementary first order theory.

**Guiding principle**. For a theory that is well-behaved from the point of view of model theory, it should be easier to understand the complexity of the models.

**Computable models**. We consider models with universe a subset of  $\omega$ . We identify a model  $\mathcal{M}$  with its atomic diagram. So,  $\mathcal{M}$  is *computable* if  $D(\mathcal{M})$ , identified with a subset of  $\omega$ , is computable.

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# **Theorem (Lerman-Schmerl)**. If T is an arithmetical $\aleph_0$ -categorical theory and for $n \ge 1$ , $T \cap \exists_{n+1}$ is $\Sigma_n^0$ , then T has a computable model.

**Theorem (K)**. If T is an  $\aleph_0$ -categorical theory and  $T \cap \exists_{n+1}$  is  $\Sigma_n^0$  uniformly in n, then T has a computable model.

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# **Theorem (Khoussainov-Montalbán)**. There is a non-arithmetical $\aleph_0$ -categorical theory with a computable model.

(The proof uses "Marker extensions", which makes the language infinite.)

Theorem (Andrews). There is such a theory in a finite language.

**Definition**. A theory *T* is *strongly minimal* if for every model  $\mathcal{M}$ , and every formula  $\varphi(\overline{a}, x)$  with parameters  $\overline{a}$  in  $\mathcal{M}$ , exactly one of  $\varphi^{\mathcal{M}}(\overline{a}, x)$ ,  $\neg \varphi^{\mathcal{M}}(\overline{a}, x)$  is infinite.

#### Familiar examples.

- 1. the theory of  $(\mathbb{Z}, S)$
- 2. the theory of infinite  $\mathbb{Q}$ -vector spaces
- 3. the theory of the field  ${\mathbb C}$  of complex numbers

# Algebraic closure and dimension

**Definition**. Let  $\mathcal{T}$  be a strongly minimal theory, and let  $\mathcal{M}$  be a model.

- 1. The algebraic closure of S, denoted by  $acl_{\mathcal{M}}(S)$ , is the union of the finite sets  $\varphi^{\mathcal{M}}(\overline{c}, x)$  definable in  $\mathcal{M}$  with parameters  $\overline{c}$  in S.
- A set I ⊆ M is algebraically independent if for all i ∈ I, i ∉ acl<sub>M</sub>({I - {i}}).

**Remark**. Algebraic closure gives a well-defined notion of dimension. Each model of T is determined, up to isomorphism, by its dimension.

**Definition**. A strongly minimal theory is *trivial* if for all models  $\mathcal{M}$  and  $S \subseteq \mathcal{M}$ ,  $acl_{\mathcal{M}}(S) = \bigcup_{s \in S} acl_{\mathcal{M}}(\{s\})$ .

**Theorem (Goncharov-Harizanov-Laskowski-Lempp-McCoy)**. Every trivial strongly minimal theory with a computable model is  $\Delta_3^0$ .

(It follows that all models have  $\Delta_3^0$  copies.)

# Complicated theories with computable models

**Goncharov-Khoussainov, Fokina**. For each *n*, there is an  $\aleph_1$ -categorical theory *T* s.t. *T* has a computable model, and *T* is not  $\Delta_n^0$ .

(The proof uses Marker extensions, so the language is infinite and the theory is not strongly minimal.)

**Andrews**. There is a non-arithmetical strongly minimal theory with a computable model.

# New results

**Main Theorem (Andrews-K)**. Let T be a strongly minimal theory in a relational language. If  $T \cap \exists_{n+3}$  is  $\Delta_n^0$ , uniformly in n, then every model of T has a computable copy.

Relativizing to  $\emptyset^{(4)}$ , we get the following.

**Corollary**. If  $\mathcal{T}$  has a computable model  $\mathcal{M}$ , then every model has a copy computable in  $\emptyset^{(4)}$  (i.e.,  $\Delta_5^0$ ).

#### Proof.

Since there is a computable model,  $T \cap \exists_n$  is  $\Delta^0_{n+1}$ , uniformly. Then  $T \cap \exists_{n+3}$  is  $\Delta^0_{n+4}$ , which is  $\Delta^0_n$  relative to  $\emptyset^{(4)}$ .

# Cases

The proof of the Main Theorem splits into cases, according to whether the theory T is arithmetical, and whether the model  $\mathcal{M}$  that we are copying is saturated, or has a "bounded" saturation property.

- 1. T is arithmetical, and  $\mathcal{M}$  is boundedly saturated.
- 2. T is not arithmetical and  $\mathcal{M}$  is saturated.
- 3. T is not arithmetical and  $\mathcal{M}$  has dimension k for some finite k, but is boundedly saturated.

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- 4.  ${\mathcal T}$  is arithmetical, and  ${\mathcal M}$  is not boundedly saturated
- 5. T is not arithmetical, and  $\mathcal{M}$  is not boundedly saturated

Bounded types and bounded saturation

#### Definition.

- 1. An *n*-formula is a Boolean combination of  $\exists_n$ -formulas.
- 2. An *n*-type is the set of *n*-formulas in a complete type.
- A model A is *n*-saturated if for all ā, every *n*-type p(ā, x) consistent with the type of ā is realized.

We need enumerations  $R^n$  of the *n*-types.

**Lemma**. There is a family  $(R^n)_{n\geq 1}$  of enumerations of the *n*-types s.t.  $R^1$  is computable, and for  $n \geq 2$ ,  $R^n$  is  $\Delta_{n-1}^0$ , uniformly in *n*.

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# Morley rank

#### Definition.

- 1. The Morley *rank of a formula* is the maximum dimension of a tuple satisfying the formula.
- 2. The *Morley rank of a type* is the minimum of the ranks of the formulas in the type.

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# Definability

**Remarks**. For each formula  $\varphi(\overline{u}, x)$ , there is some k s.t. for any model  $\mathcal{A}$  and any  $\overline{a}$  in  $\mathcal{A}$ , only one of  $\varphi^{\mathcal{A}}(\overline{a}, x)$ ,  $\neg \varphi^{\mathcal{A}}(\overline{a}, x)$  has size  $\geq k$ . Then

$$\mathcal{A}\models (\exists^{\geq k}x) \varphi(\overline{a},x) 
ightarrow (\exists^{\infty}x) \varphi(\overline{a},x)$$

For an *n*-formula  $\varphi(\overline{u}, x)$ , we find the appropriate *k* as above using  $T \cap \exists_{n+1}$ . For a  $\exists_{n+1}$  formula, we can find the appropriate *k* using  $T \cap \exists_{n+2}$ .

# Rank and the enumerations of types

**Lemma**. For an *n*-formula  $\varphi(\overline{x})$ , using  $T \cap \exists_{n+2}$ , we can find  $\exists_{n+1}$  formulas saying that  $\varphi(\overline{x})$  has rank at least *k*. Then using  $T \cap \exists_{n+2}$ , we can determine the rank.

For the enumeration  $\mathbb{R}^n$  in Lemma 1, for each  $\overline{x}$ , we list the type of full rank first. When we see a split, with one side having lower rank, the current index stays with the type of higher rank, and we add a new index for the type of lower rank.

**Definition**. Let  $\mathcal{M}$  be a model of T with universe  $\omega$ . The  $\mathbb{R}^n$ -labeling for  $\mathcal{M}$  is the function taking each tuple  $\overline{a}$  in  $\mathcal{M}$  to the  $\mathbb{R}^n$ -index for the type.

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# Case 1-T is arithmetical and $\mathcal{M}$ is boundedly saturated

**Lemma 1 (Harrington, Khisamiev)**. Suppose T is strongly minimal. If T is  $\Delta_N^0$ , then every model of T has a copy whose complete diagram is  $\Delta_N^0$ .

**Lemma 2.** Suppose  $R^N$  is  $\Delta_N^0$ . If  $\mathcal{M}$  is a model whose complete diagram is  $\Delta_N^0$ , then the  $R^N$ -labeling of  $\mathcal{M}$  is  $\Delta_{N+1}^0$ .

**Lemma 3**. For  $n \ge 2$ , if  $\mathcal{M}$  is an *n*-saturated model with a  $\Delta_{n+1}^0$   $\mathbb{R}^n$ -labeling, then there is a copy with a  $\Delta_n^0 \mathbb{R}^{n-1}$ -labeling.

**Lemma 4**. If  $\mathcal{M}$  is a 1-saturated model of  $\mathcal{T}$  with a  $\Delta_2^0 R^1$ -labeling, then there is a computable copy.

In the proofs of Lemmas 3 and 4, bounded saturation helps us map elements of the copy we are building to elements of the given model.

# Putting the pieces together for Case 1

Suppose T is  $\Delta_N^0$ , and  $\mathcal{M}$  is N-saturated. First, we apply Lemmas 1 and 2 to get a copy of  $\mathcal{M}$  with a  $\Delta_{N+1}^0 R^N$ -labeling. Then we work our way down, applying Lemma 3 until we have a copy with a  $\Delta_2^0 R^1$ -labeling. Finally, we apply Lemma 4 to get a computable copy.

## Case 2—T is not arithmetical and $\mathcal{M}$ is saturated

We build a copy  $\mathcal{A}$  of the saturated model "on the diagonal"; i.e., the  $\Delta_3^0$  worker carries out the first step, assigning a 3-type to a first element, the  $\Delta_4^0$  worker carries out the second step, assigning a 4-type to the first two elements, etc. At even steps, the new element is designated as generic—helping to build the saturated model, and at odd steps, the new element is a witness as in the standerd Henkin construction.

For each  $n \geq 3$ , after contributing to the diagonal, the  $\Delta_n^0$  worker goes into guessing mode, giving an  $\mathbb{R}^{n-1}$ -labeling for a structure  $\mathcal{B}_n$ , based on guesses at the  $\mathbb{R}^n$ -labeling produced by the  $\Delta_{n+1}^0$ worker. It takes effort to show that the  $\mathcal{B}_n$  are all isomorphic, and that they are isomorphic to  $\mathcal{A}$ .

### Models that are not boundedly saturated

If  $\mathcal{M}$  is not *n*-saturated, we have a tuple  $\overline{a}$  with an *n*-type  $p(\overline{a}, x)$  that is consistent with the type of  $\overline{a}$  but is not realized in  $\mathcal{M}$ . The type  $p(\overline{a}, x)$  is the type of an *n*-generic over  $\overline{a}$ . Every element *b* satisfies some algebraic *n*-formula  $\psi(\overline{a}, x)$ . We can use this, for Cases 4 and 5, in the same way that we used bounded saturation.