

Dimension dependence of factorization problems

Structures in Banach Spaces

Thomas Speckhofer

Institute of Analysis
Johannes Kepler University Linz, Austria

March 18, 2025

1 Dimension dependence of factorization problems

 T. Speckhofer. *Dimension dependence of factorization problems: Haar system Hardy spaces*. *Studia Mathematica*, to appear.

1 Dimension dependence of factorization problems



T. Speckhofer. *Dimension dependence of factorization problems: Haar system Hardy spaces*. *Studia Mathematica*, to appear.

Definitions

- Dyadic intervals: $\mathcal{D} = \{[0, 1), [0, \frac{1}{2}), [\frac{1}{2}, 1), [0, \frac{1}{4}), [\frac{1}{4}, \frac{1}{2}), \dots\}$
- $I^+ =$ left half, $I^- =$ right half of $I \in \mathcal{D}$
- Define $h_I = \mathbb{1}_{I^+} - \mathbb{1}_{I^-}$, $I \in \mathcal{D}$.
- A **Haar system space** X is the completion of $H = \text{span}\{\mathbb{1}_{[0,1)}, h_I : I \in \mathcal{D}\}$ under a norm $\|\cdot\|_X$ such that:
 - If $x, y \in H$ and $|x|, |y|$ have the same distribution, then $\|x\|_X = \|y\|_X$.
 - $\|\mathbb{1}_{[0,1)}\|_X = 1$.
- Examples: L^p , $1 \leq p < \infty$, all separable rearrangement-invariant function spaces on $[0, 1)$

Definitions

- Dyadic intervals: $\mathcal{D} = \{[0, 1), [0, \frac{1}{2}), [\frac{1}{2}, 1), [0, \frac{1}{4}), [\frac{1}{4}, \frac{1}{2}), \dots\}$
- $I^+ =$ left half, $I^- =$ right half of $I \in \mathcal{D}$
- Define $h_I = \mathbb{1}_{I^+} - \mathbb{1}_{I^-}$, $I \in \mathcal{D}$.
- A **Haar system space** X is the completion of $H = \text{span}\{\mathbb{1}_{[0,1)}, h_I : I \in \mathcal{D}\}$ under a norm $\|\cdot\|_X$ such that:
 - If $x, y \in H$ and $|x|, |y|$ have the same distribution, then $\|x\|_X = \|y\|_X$.
 - $\|\mathbb{1}_{[0,1)}\|_X = 1$.
- Examples: L^p , $1 \leq p < \infty$, all separable rearrangement-invariant function spaces on $[0, 1)$

Definitions

- Dyadic intervals: $\mathcal{D} = \{[0, 1), [0, \frac{1}{2}), [\frac{1}{2}, 1), [0, \frac{1}{4}), [\frac{1}{4}, \frac{1}{2}), \dots\}$
- $I^+ =$ left half, $I^- =$ right half of $I \in \mathcal{D}$
- Define $h_I = \mathbb{1}_{I^+} - \mathbb{1}_{I^-}$, $I \in \mathcal{D}$.
- A **Haar system space** X is the completion of $H = \text{span}\{\mathbb{1}_{[0,1)}, h_I : I \in \mathcal{D}\}$ under a norm $\|\cdot\|_X$ such that:
 - If $x, y \in H$ and $|x|, |y|$ have the same distribution, then $\|x\|_X = \|y\|_X$.
 - $\|\mathbb{1}_{[0,1)}\|_X = 1$.
- Examples: L^p , $1 \leq p < \infty$, all separable rearrangement-invariant function spaces on $[0, 1)$

Definitions

- Dyadic intervals: $\mathcal{D} = \{[0, 1), [0, \frac{1}{2}), [\frac{1}{2}, 1), [0, \frac{1}{4}), [\frac{1}{4}, \frac{1}{2}), \dots\}$
- $I^+ =$ left half, $I^- =$ right half of $I \in \mathcal{D}$
- Define $h_I = \mathbb{1}_{I^+} - \mathbb{1}_{I^-}$, $I \in \mathcal{D}$.
- A **Haar system space** X is the completion of $H = \text{span}\{\mathbb{1}_{[0,1)}, h_I : I \in \mathcal{D}\}$ under a norm $\|\cdot\|_X$ such that:
 - If $x, y \in H$ and $|x|, |y|$ have the same distribution, then $\|x\|_X = \|y\|_X$.
 - $\|\mathbb{1}_{[0,1)}\|_X = 1$.
- Examples: L^p , $1 \leq p < \infty$, all separable rearrangement-invariant function spaces on $[0, 1)$

Definitions

- Dyadic intervals: $\mathcal{D} = \{[0, 1), [0, \frac{1}{2}), [\frac{1}{2}, 1), [0, \frac{1}{4}), [\frac{1}{4}, \frac{1}{2}), \dots\}$
- $I^+ =$ left half, $I^- =$ right half of $I \in \mathcal{D}$
- Define $h_I = \mathbb{1}_{I^+} - \mathbb{1}_{I^-}$, $I \in \mathcal{D}$.
- A **Haar system space** X is the completion of $H = \text{span}\{\mathbb{1}_{[0,1)}, h_I : I \in \mathcal{D}\}$ under a norm $\|\cdot\|_X$ such that:
 - If $x, y \in H$ and $|x|, |y|$ have the same distribution, then $\|x\|_X = \|y\|_X$.
 - $\|\mathbb{1}_{[0,1)}\|_X = 1$.
- Examples: L^p , $1 \leq p < \infty$, all separable rearrangement-invariant function spaces on $[0, 1)$

Definitions

- Dyadic intervals: $\mathcal{D} = \{[0, 1), [0, \frac{1}{2}), [\frac{1}{2}, 1), [0, \frac{1}{4}), [\frac{1}{4}, \frac{1}{2}), \dots\}$
- $I^+ =$ left half, $I^- =$ right half of $I \in \mathcal{D}$
- Define $h_I = \mathbb{1}_{I^+} - \mathbb{1}_{I^-}$, $I \in \mathcal{D}$.
- A **Haar system space** X is the completion of $H = \text{span}\{\mathbb{1}_{[0,1)}, h_I : I \in \mathcal{D}\}$ under a norm $\|\cdot\|_X$ such that:
 - If $x, y \in H$ and $|x|, |y|$ have the same distribution, then $\|x\|_X = \|y\|_X$.
 - $\|\mathbb{1}_{[0,1)}\|_X = 1$.
- Examples: L^p , $1 \leq p < \infty$, all separable rearrangement-invariant function spaces on $[0, 1)$

Definitions

- Dyadic intervals: $\mathcal{D} = \{[0, 1), [0, \frac{1}{2}), [\frac{1}{2}, 1), [0, \frac{1}{4}), [\frac{1}{4}, \frac{1}{2}), \dots\}$
- $I^+ =$ left half, $I^- =$ right half of $I \in \mathcal{D}$
- Define $h_I = \mathbb{1}_{I^+} - \mathbb{1}_{I^-}$, $I \in \mathcal{D}$.
- A **Haar system space** X is the completion of $H = \text{span}\{\mathbb{1}_{[0,1)}, h_I : I \in \mathcal{D}\}$ under a norm $\|\cdot\|_X$ such that:
 - If $x, y \in H$ and $|x|, |y|$ have the same distribution, then $\|x\|_X = \|y\|_X$.
 - $\|\mathbb{1}_{[0,1)}\|_X = 1$.
- Examples: L^p , $1 \leq p < \infty$, all separable rearrangement-invariant function spaces on $[0, 1)$

Definitions

- **Haar system Hardy space** = completion of $\text{span}\{h_I : I \in \mathcal{D}\}$ under a rearrangement-invariant norm $\|\cdot\|_X$ or under $\|\cdot\|_\circ$, where

$$\left\| \sum_{I \in \mathcal{D}} a_I h_I \right\|_\circ = \left\| \left(\sum_{I \in \mathcal{D}} a_I^2 h_I^2 \right)^{1/2} \right\|_X.$$

- If $X = L^1$, then $\|\cdot\|_\circ = \|\cdot\|_{H^1}$.
- From now on, let Y be a fixed Haar system Hardy space.

Definitions

- **Haar system Hardy space** = completion of $\text{span}\{h_I : I \in \mathcal{D}\}$ under a rearrangement-invariant norm $\|\cdot\|_X$ or under $\|\cdot\|_\circ$, where

$$\left\| \sum_{I \in \mathcal{D}} a_I h_I \right\|_\circ = \left\| \left(\sum_{I \in \mathcal{D}} a_I^2 h_I^2 \right)^{1/2} \right\|_X.$$

- If $X = L^1$, then $\|\cdot\|_\circ = \|\cdot\|_{H^1}$.
- From now on, let Y be a fixed Haar system Hardy space.

Definitions

- **Haar system Hardy space** = completion of $\text{span}\{h_I : I \in \mathcal{D}\}$ under a rearrangement-invariant norm $\|\cdot\|_X$ or under $\|\cdot\|_\circ$, where

$$\left\| \sum_{I \in \mathcal{D}} a_I h_I \right\|_\circ = \left\| \left(\sum_{I \in \mathcal{D}} a_I^2 h_I^2 \right)^{1/2} \right\|_X.$$

- If $X = L^1$, then $\|\cdot\|_\circ = \|\cdot\|_{H^1}$.
- From now on, let Y be a fixed Haar system Hardy space.

Definitions

- **Haar system Hardy space** = completion of $\text{span}\{h_I : I \in \mathcal{D}\}$ under a rearrangement-invariant norm $\|\cdot\|_X$ or under $\|\cdot\|_\circ$, where

$$\left\| \sum_{I \in \mathcal{D}} a_I h_I \right\|_\circ = \left\| \left(\sum_{I \in \mathcal{D}} a_I^2 h_I^2 \right)^{1/2} \right\|_X.$$

- If $X = L^1$, then $\|\cdot\|_\circ = \|\cdot\|_{H^1}$.
- From now on, let Y be a fixed Haar system Hardy space.

Dimension dependence: Introduction

- For $n \in \mathbb{N}_0$, let $Y_n = \text{span}\{h_I : |I| \geq 2^{-n}\} \subset Y$.
- Given $n \in \mathbb{N}_0, \delta > 0$, how large does $N \in \mathbb{N}_0$ have to be chosen such that for every operator $T: Y_N \rightarrow Y_N$ with $\|T\| \leq 1$ and with δ -large positive diagonal, there exists a factorization

$$\begin{array}{ccc} Y_n & \xrightarrow{I_{Y_n}} & Y_n \\ B \downarrow & & \uparrow A \\ Y_N & \xrightarrow{T} & Y_N \end{array}$$

where $\|A\|\|B\| \leq (1 + \varepsilon)/\delta$? (\rightarrow factorization constant)

- Variant: no “large diagonal”, but factorization through T or $I_{Y_N} - T$.

Dimension dependence: Introduction

- For $n \in \mathbb{N}_0$, let $Y_n = \text{span}\{h_I : |I| \geq 2^{-n}\} \subset Y$.
- Given $n \in \mathbb{N}_0, \delta > 0$, how large does $N \in \mathbb{N}_0$ have to be chosen such that for every operator $T: Y_N \rightarrow Y_N$ with $\|T\| \leq 1$ and with δ -large positive diagonal, there exists a factorization

$$\begin{array}{ccc} Y_n & \xrightarrow{I_{Y_n}} & Y_n \\ B \downarrow & & \uparrow A \\ Y_N & \xrightarrow{T} & Y_N \end{array}$$

where $\|A\|\|B\| \leq (1 + \varepsilon)/\delta$? (\rightarrow factorization constant)

- Variant: no “large diagonal”, but factorization through T or $I_{Y_N} - T$.

Dimension dependence: Introduction

- For $n \in \mathbb{N}_0$, let $Y_n = \text{span}\{h_I : |I| \geq 2^{-n}\} \subset Y$.
- Given $n \in \mathbb{N}_0, \delta > 0$, how large does $N \in \mathbb{N}_0$ have to be chosen such that for every operator $T: Y_N \rightarrow Y_N$ with $\|T\| \leq 1$ and with δ -large positive diagonal, there exists a factorization

$$\begin{array}{ccc} Y_n & \xrightarrow{I_{Y_n}} & Y_n \\ B \downarrow & & \uparrow A \\ Y_N & \xrightarrow{T} & Y_N \end{array}$$

where $\|A\|\|B\| \leq (1 + \varepsilon)/\delta$? (\rightarrow factorization constant)

- Variant: no “large diagonal”, but factorization through T or $I_{Y_N} - T$.

Dimension dependence: Introduction

- For $n \in \mathbb{N}_0$, let $Y_n = \text{span}\{h_I : |I| \geq 2^{-n}\} \subset Y$.
- Given $n \in \mathbb{N}_0, \delta > 0$, how large does $N \in \mathbb{N}_0$ have to be chosen such that for every operator $T: Y_N \rightarrow Y_N$ with $\|T\| \leq 1$ and with δ -large positive diagonal, there exists a factorization

$$\begin{array}{ccc} Y_n & \xrightarrow{I_{Y_n}} & Y_n \\ B \downarrow & & \uparrow A \\ Y_N & \xrightarrow{T} & Y_N \end{array}$$

where $\|A\|\|B\| \leq (1 + \varepsilon)/\delta$? (\rightarrow factorization constant)

- Variant: no “large diagonal”, but factorization through T or $I_{Y_N} - T$.

Dimension dependence: Introduction

- In L^p , $1 \leq p \leq \infty$:
 Restricted Invertibility Theorem (Bourgain-Tzafriri 1987)
 → linear dimension dependence
- Conversely: factorization $\implies T$ “well invertible” on a large subspace
- Bourgain’s localization method may yield primariness
- Results in other classical spaces:
 $\mathcal{B}(\ell^2)$ (Blower), H^1 and BMO (Müller), $\ell^\infty(L^p)$ (Wark), ...
- Existing bounds for N are often super-exponential functions of n
- Lechner 2019: $N \geq Cn$ is sufficient in H^p , $1 \leq p < \infty$, and SL^∞ .

Dimension dependence: Introduction

- In L^p , $1 \leq p \leq \infty$:
 Restricted Invertibility Theorem (Bourgain-Tzafriri 1987)
 → linear dimension dependence
- Conversely: factorization $\implies T$ “well invertible” on a large subspace
- Bourgain’s localization method may yield primariness
- Results in other classical spaces:
 $\mathcal{B}(\ell^2)$ (Blower), H^1 and BMO (Müller), $\ell^\infty(L^p)$ (Wark), ...
- Existing bounds for N are often super-exponential functions of n
- Lechner 2019: $N \geq Cn$ is sufficient in H^p , $1 \leq p < \infty$, and SL^∞ .

Dimension dependence: Introduction

- In L^p , $1 \leq p \leq \infty$:
 Restricted Invertibility Theorem (Bourgain-Tzafriri 1987)
 → linear dimension dependence
- Conversely: factorization $\implies T$ “well invertible” on a large subspace
- Bourgain’s localization method may yield primariness
- Results in other classical spaces:
 $\mathcal{B}(\ell^2)$ (Blower), H^1 and BMO (Müller), $\ell^\infty(L^p)$ (Wark), ...
- Existing bounds for N are often super-exponential functions of n
- Lechner 2019: $N \geq Cn$ is sufficient in H^p , $1 \leq p < \infty$, and SL^∞ .

Dimension dependence: Introduction

- In L^p , $1 \leq p \leq \infty$:
 Restricted Invertibility Theorem (Bourgain-Tzafriri 1987)
 \rightarrow linear dimension dependence
- Conversely: factorization $\implies T$ “well invertible” on a large subspace
- Bourgain’s localization method may yield primariness
- Results in other classical spaces:
 $\mathcal{B}(\ell^2)$ (Blower), H^1 and BMO (Müller), $\ell^\infty(L^p)$ (Wark), ...
- Existing bounds for N are often super-exponential functions of n
- Lechner 2019: $N \geq Cn$ is sufficient in H^p , $1 \leq p < \infty$, and SL^∞ .

Dimension dependence: Introduction

- In L^p , $1 \leq p \leq \infty$:
 Restricted Invertibility Theorem (Bourgain-Tzafriri 1987)
 → linear dimension dependence
- Conversely: factorization $\implies T$ “well invertible” on a large subspace
- Bourgain’s localization method may yield primariness
- Results in other classical spaces:
 $\mathcal{B}(\ell^2)$ (Blower), H^1 and BMO (Müller), $\ell^\infty(L^p)$ (Wark), ...
- Existing bounds for N are often super-exponential functions of n
- Lechner 2019: $N \geq Cn$ is sufficient in H^p , $1 \leq p < \infty$, and SL^∞ .

Dimension dependence: Introduction

- In L^p , $1 \leq p \leq \infty$:
 Restricted Invertibility Theorem (Bourgain-Tzafriri 1987)
 \rightarrow linear dimension dependence
- Conversely: factorization $\implies T$ “well invertible” on a large subspace
- Bourgain’s localization method may yield primariness
- Results in other classical spaces:
 $\mathcal{B}(\ell^2)$ (Blower), H^1 and BMO (Müller), $\ell^\infty(L^p)$ (Wark), ...
- Existing bounds for N are often super-exponential functions of n
- Lechner 2019: $N \geq Cn$ is sufficient in H^p , $1 \leq p < \infty$, and SL^∞ .

Dimension dependence: Introduction

- In L^p , $1 \leq p \leq \infty$:
Restricted Invertibility Theorem (Bourgain-Tzafriri 1987)
→ linear dimension dependence
- Conversely: factorization $\implies T$ “well invertible” on a large subspace
- Bourgain’s localization method may yield primariness
- Results in other classical spaces:
 $\mathcal{B}(\ell^2)$ (Blower), H^1 and BMO (Müller), $\ell^\infty(L^p)$ (Wark), ...
- Existing bounds for N are often super-exponential functions of n
- Lechner 2019: $N \geq Cn$ is sufficient in H^p , $1 \leq p < \infty$, and SL^∞ .

Main results

Theorem (S. '24)

Let Y be a Haar system Hardy space and $\varepsilon > 0$. Put $\eta = \frac{\varepsilon}{6(1+\varepsilon)}$. If

$$N \geq 42n(n+1) \left\lceil \frac{1}{\eta} \right\rceil + 42 + \left\lfloor 4 \log_2 \left(\frac{1}{\eta} \right) \right\rfloor, \quad (1)$$

then for every linear operator $T: Y_N \rightarrow Y_N$ with $\|T\| \leq 1$, the identity I_{Y_n} factors through T or $I_{Y_N} - T$ with constant $2(1 + \varepsilon)$.

If $(h_I)_I$ is K -unconditional in Y , then (1) can be replaced by

$$N \geq C(\eta, K) n.$$

Main results

Theorem (S. '24)

Let Y be a Haar system Hardy space and $\varepsilon > 0$. Put $\eta = \frac{\varepsilon}{6(1+\varepsilon)}$. If

$$N \geq 42n(n+1) \left\lceil \frac{1}{\eta} \right\rceil + 42 + \left\lfloor 4 \log_2 \left(\frac{1}{\eta} \right) \right\rfloor, \quad (1)$$

then for every linear operator $T: Y_N \rightarrow Y_N$ with $\|T\| \leq 1$, the identity I_{Y_n} factors through T or $I_{Y_N} - T$ with constant $2(1 + \varepsilon)$.

If $(h_I)_I$ is K -unconditional in Y , then (1) can be replaced by

$$N \geq C(\eta, K) n.$$

Main results

Theorem (S. '24)

Let Y be a Haar system Hardy space and $\varepsilon > 0$. Put $\eta = \frac{\varepsilon}{6(1+\varepsilon)}$. If

$$N \geq C(\eta) n^2, \quad (1)$$

then for every linear operator $T: Y_N \rightarrow Y_N$ with $\|T\| \leq 1$, the identity I_{Y_n} factors through T or $I_{Y_N} - T$ with constant $2(1 + \varepsilon)$.

If $(h_I)_I$ is K -unconditional in Y , then (1) can be replaced by

$$N \geq C(\eta, K) n.$$

Main results

Theorem (S. '24)

Let Y be a Haar system Hardy space and $\varepsilon > 0$. Put $\eta = \frac{\varepsilon}{6(1+\varepsilon)}$. If

$$N \geq C(\eta) n^2, \quad (1)$$

then for every linear operator $T: Y_N \rightarrow Y_N$ with $\|T\| \leq 1$, the identity I_{Y_n} factors through T or $I_{Y_N} - T$ with constant $2(1 + \varepsilon)$.

If $(h_I)_I$ is K -unconditional in Y , then (1) can be replaced by

$$N \geq C(\eta, K) n.$$

Main results

Theorem (S. '24)

Let Y be a Haar system Hardy space and $\delta, \varepsilon > 0$. Put $\eta = \frac{\varepsilon\delta}{6(1+\varepsilon)}$. If

$$N \geq C(\eta) n^2, \quad (1)$$

then for every linear operator $T: Y_N \rightarrow Y_N$ with $\|T\| \leq 1$ and with δ -large positive diagonal, the identity I_{Y_n} factors through T with constant $(1+\varepsilon)/\delta$. If $(h_I)_I$ is K -unconditional in Y , then (1) can be replaced by

$$N \geq C(\eta, K) n.$$

Corollary (S. '24)

If $N \geq C n^4 2^{C n^2}$, where $C = C(\eta, \delta)$, then the word “positive” can be omitted (this doubles the factorization constant).

Main results

Theorem (S. '24)

Let Y be a Haar system Hardy space and $\delta, \varepsilon > 0$. Put $\eta = \frac{\varepsilon\delta}{6(1+\varepsilon)}$. If

$$N \geq C(\eta) n^2, \quad (1)$$

then for every linear operator $T: Y_N \rightarrow Y_N$ with $\|T\| \leq 1$ and with δ -large positive diagonal, the identity I_{Y_n} factors through T with constant $(1+\varepsilon)/\delta$. If $(h_I)_I$ is K -unconditional in Y , then (1) can be replaced by

$$N \geq C(\eta, K) n.$$

Corollary (S. '24)

If $N \geq C n^4 2^{C n^2}$, where $C = C(\varepsilon, \delta)$, then the word “positive” can be omitted (this doubles the factorization constant).

Proof method

- Basic idea: Step-by-step reduction

Operator $T \rightarrow$ Haar multiplier $D \rightarrow$ constant multiple of the identity cI_{Y_n}

- Clearly, the identity I_{Y_n} factors through cI_{Y_n} or $(1-c)I_{Y_n}$.

$$D \approx A_1 T B_1, \quad cI_{Y_n} \approx A_2 D B_2$$

- How are A_i, B_i defined? \rightarrow faithful Haar system $(\hat{h}_I)_I$,
Associated operators A, B :

$$Bx = \sum_I \frac{\langle h_I, x \rangle}{|I|} \hat{h}_I, \quad Ax = \sum_I \frac{\langle \hat{h}_I, x \rangle}{|I|} h_I$$

Proof method

- Basic idea: Step-by-step reduction

Operator $T \rightarrow$ Haar multiplier $D \rightarrow$ constant multiple of the identity cI_{Y_n}

- Clearly, the identity I_{Y_n} factors through cI_{Y_n} or $(1 - c)I_{Y_n}$.

$$D \approx A_1 T B_1, \quad cI_{Y_n} \approx A_2 D B_2$$

- How are A_i, B_i defined? \rightarrow faithful Haar system $(\hat{h}_I)_I$,
Associated operators A, B :

$$Bx = \sum_I \frac{\langle h_I, x \rangle}{|I|} \hat{h}_I, \quad Ax = \sum_I \frac{\langle \hat{h}_I, x \rangle}{|I|} h_I$$

Proof method

- Basic idea: Step-by-step reduction
Operator $T \rightarrow$ Haar multiplier $D \rightarrow$ constant multiple of the identity cI_{Y_n}
- Clearly, the identity I_{Y_n} factors through cI_{Y_n} or $(1 - c)I_{Y_n}$.

$$D \approx A_1 T B_1, \quad cI_{Y_n} \approx A_2 D B_2$$

- How are A_i, B_i defined? \rightarrow faithful Haar system $(\hat{h}_I)_I$,
Associated operators A, B :

$$Bx = \sum_I \frac{\langle h_I, x \rangle}{|I|} \hat{h}_I, \quad Ax = \sum_I \frac{\langle \hat{h}_I, x \rangle}{|I|} h_I$$

Proof method

- Basic idea: Step-by-step reduction
Operator $T \rightarrow$ Haar multiplier $D \rightarrow$ constant multiple of the identity cI_{Y_n}
- Clearly, the identity I_{Y_n} factors through cI_{Y_n} or $(1 - c)I_{Y_n}$.

$$D \approx A_1 T B_1, \quad cI_{Y_n} \approx A_2 D B_2$$

- How are A_i, B_i defined? \rightarrow *faithful Haar system* $(\hat{h}_I)_I$,
Associated operators A, B :

$$Bx = \sum_I \frac{\langle h_I, x \rangle}{|I|} \hat{h}_I, \quad Ax = \sum_I \frac{\langle \hat{h}_I, x \rangle}{|I|} h_I$$

Proof method

- Basic idea: Step-by-step reduction
Operator $T \rightarrow$ Haar multiplier $D \rightarrow$ constant multiple of the identity cI_{Y_n}
- Clearly, the identity I_{Y_n} factors through cI_{Y_n} or $(1 - c)I_{Y_n}$.

$$D \approx A_1 T B_1, \quad cI_{Y_n} \approx A_2 D B_2$$

- How are A_i, B_i defined? \rightarrow *faithful Haar system* $(\hat{h}_I)_I$,
Associated operators A, B :

$$Bx = \sum_I \frac{\langle h_I, x \rangle}{|I|} \hat{h}_I, \quad Ax = \sum_I \frac{\langle \hat{h}_I, x \rangle}{|I|} h_I$$

Proof method

- Basic idea: Step-by-step reduction
Operator $T \rightarrow$ Haar multiplier $D \rightarrow$ constant multiple of the identity cI_{Y_n}
- Clearly, the identity I_{Y_n} factors through cI_{Y_n} or $(1 - c)I_{Y_n}$.

$$D \approx A_1 T B_1, \quad cI_{Y_n} \approx A_2 D B_2$$

- How are A_i, B_i defined? \rightarrow *faithful Haar system* $(\hat{h}_I)_I$,
Associated operators A, B :

$$Bx = \sum_I \frac{\langle h_I, x \rangle}{|I|} \hat{h}_I, \quad Ax = \sum_I \frac{\langle \hat{h}_I, x \rangle}{|I|} h_I$$

Proof method

- Basic idea: Step-by-step reduction
Operator $T \rightarrow$ Haar multiplier $D \rightarrow$ constant multiple of the identity cI_{Y_n}
- Clearly, the identity I_{Y_n} factors through cI_{Y_n} or $(1 - c)I_{Y_n}$.

$$D \approx A_1 T B_1, \quad cI_{Y_n} \approx A_2 D B_2$$

- How are A_i, B_i defined? \rightarrow *faithful Haar system* $(\hat{h}_I)_I$,
Associated operators A, B :

$$Bx = \sum_I \frac{\langle h_I, x \rangle}{|I|} \hat{h}_I, \quad Ax = \sum_I \frac{\langle \hat{h}_I, x \rangle}{|I|} h_I$$

Proof method

- Basic idea: Step-by-step reduction
Operator $T \rightarrow$ Haar multiplier $D \rightarrow$ constant multiple of the identity cI_{Y_n}
- Clearly, the identity I_{Y_n} factors through cI_{Y_n} or $(1 - c)I_{Y_n}$.

$$D \approx A_1 T B_1, \quad cI_{Y_n} \approx A_2 D B_2$$

- How are A_i, B_i defined? \rightarrow *faithful Haar system* $(\hat{h}_I)_I$,
Associated operators A, B :

$$Bx = \sum_I \frac{\langle h_I, x \rangle}{|I|} \hat{h}_I, \quad Ax = \sum_I \frac{\langle \hat{h}_I, x \rangle}{|I|} h_I$$

Proof method

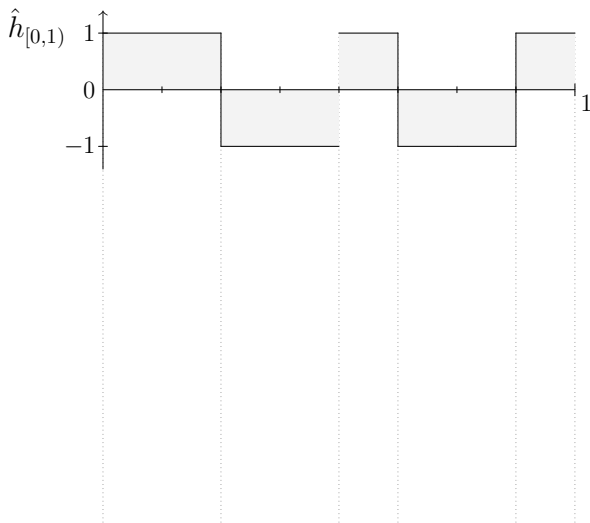
- Basic idea: Step-by-step reduction
Operator $T \rightarrow$ Haar multiplier $D \rightarrow$ constant multiple of the identity cI_{Y_n}
- Clearly, the identity I_{Y_n} factors through cI_{Y_n} or $(1 - c)I_{Y_n}$.

$$D \approx A_1 T B_1, \quad cI_{Y_n} \approx A_2 D B_2$$

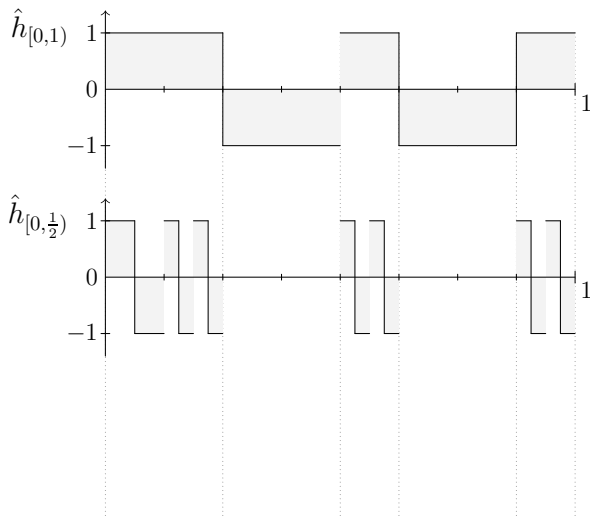
- How are A_i, B_i defined? \rightarrow *faithful Haar system* $(\hat{h}_I)_I$,
Associated operators A, B :

$$Bx = \sum_I \frac{\langle h_I, x \rangle}{|I|} \hat{h}_I, \quad Ax = \sum_I \frac{\langle \hat{h}_I, x \rangle}{|I|} h_I$$

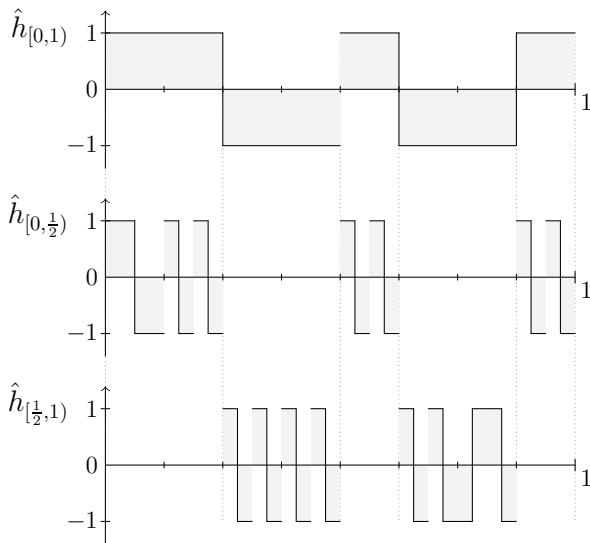
Faithful Haar system



Faithful Haar system



Faithful Haar system



Proof: Diagonalization

First step: *diagonalization via random faithful Haar systems*

- Choose signs $\theta = (\theta_K)_{K \in \mathcal{D}} \in \{\pm 1\}^{\mathcal{D}}$ uniformly at random.
- Construct a (finite) randomized faithful Haar system by

$$\hat{h}_I(\theta) = \sum_{K \in \mathcal{B}_I(\theta)} \theta_K h_K, \quad |I| \geq 2^{-Cn^2},$$

where $\mathcal{B}_I(\theta) \subset \mathcal{D}$.

Proof: Diagonalization

First step: *diagonalization via random faithful Haar systems*

- Choose signs $\theta = (\theta_K)_{K \in \mathcal{D}} \in \{\pm 1\}^{\mathcal{D}}$ uniformly at random.
- Construct a (finite) randomized faithful Haar system by

$$\hat{h}_I(\theta) = \sum_{K \in \mathcal{B}_I(\theta)} \theta_K h_K, \quad |I| \geq 2^{-Cn^2},$$

where $\mathcal{B}_I(\theta) \subset \mathcal{D}$.

Proof: Diagonalization

First step: *diagonalization via random faithful Haar systems*

- Choose signs $\theta = (\theta_K)_{K \in \mathcal{D}} \in \{\pm 1\}^{\mathcal{D}}$ uniformly at random.
- Construct a (finite) randomized faithful Haar system by

$$\hat{h}_I(\theta) = \sum_{K \in \mathcal{B}_I(\theta)} \theta_K h_K, \quad |I| \geq 2^{-Cn^2},$$

where $\mathcal{B}_I(\theta) \subset \mathcal{D}$.

Proof: Diagonalization

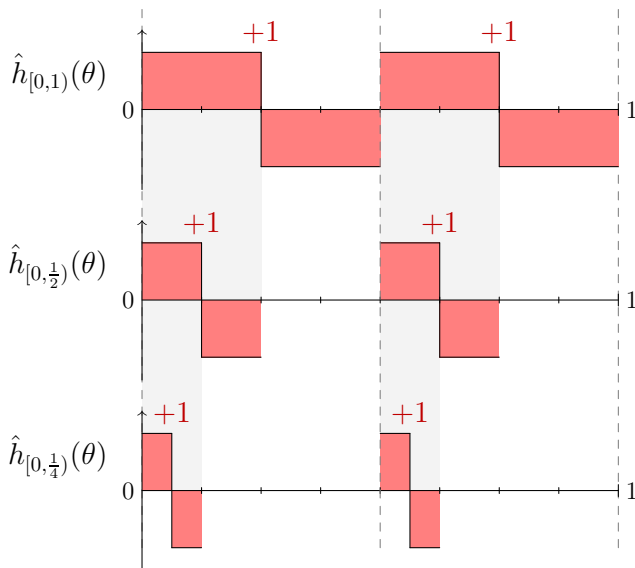
First step: *diagonalization via random faithful Haar systems*

- Choose signs $\theta = (\theta_K)_{K \in \mathcal{D}} \in \{\pm 1\}^{\mathcal{D}}$ uniformly at random.
- Construct a (finite) randomized faithful Haar system by

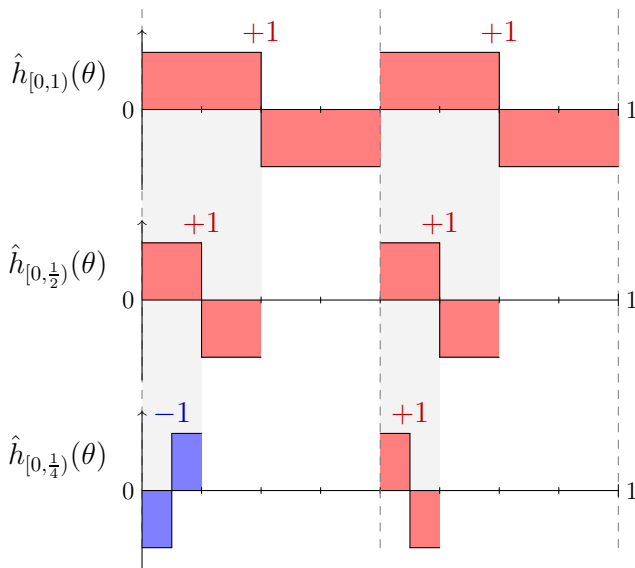
$$\hat{h}_I(\theta) = \sum_{K \in \mathcal{B}_I(\theta)} \theta_K h_K, \quad |I| \geq 2^{-Cn^2},$$

where $\mathcal{B}_I(\theta) \subset \mathcal{D}$.

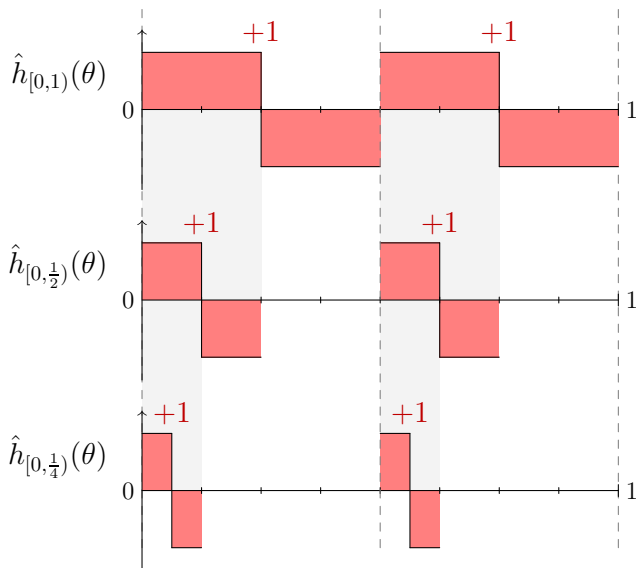
Proof: Diagonalization



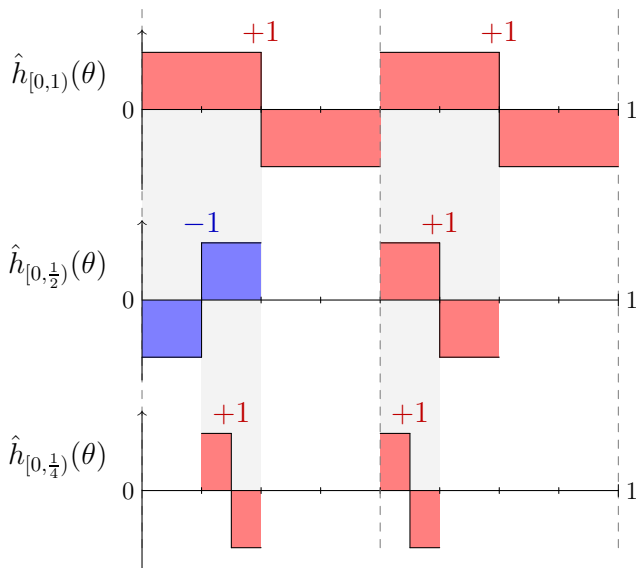
Proof: Diagonalization



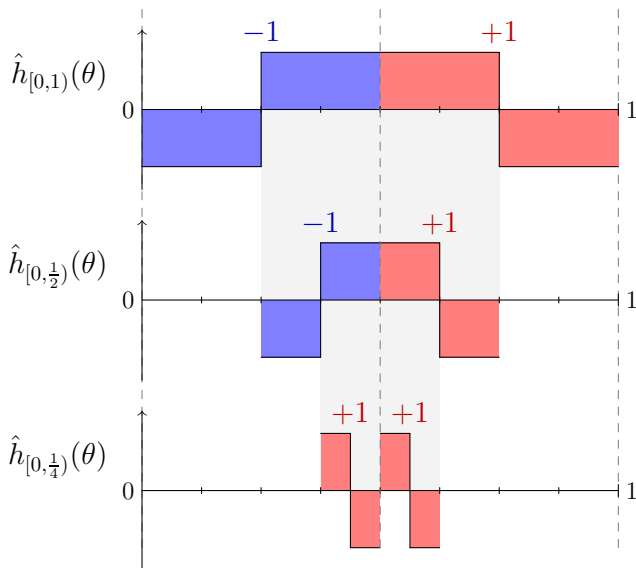
Proof: Diagonalization



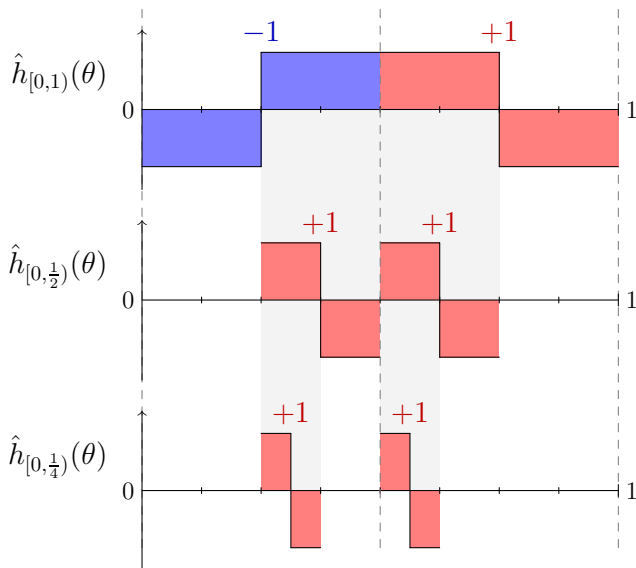
Proof: Diagonalization



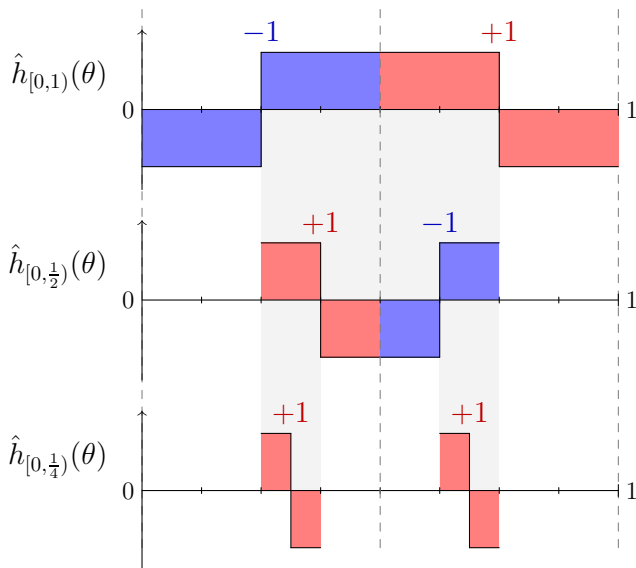
Proof: Diagonalization



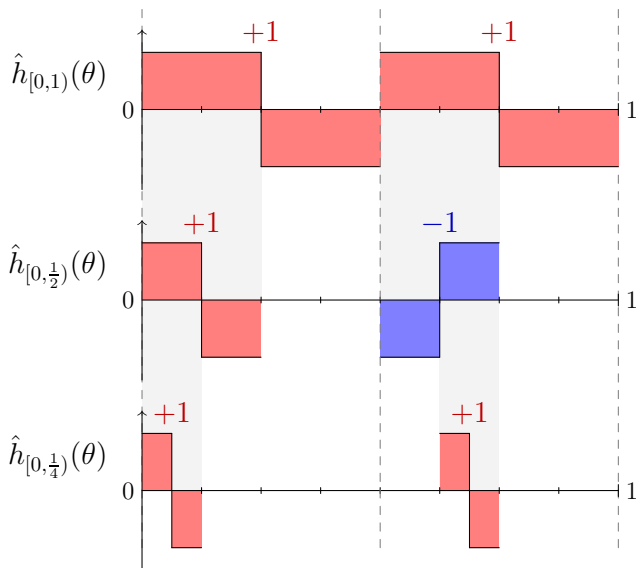
Proof: Diagonalization



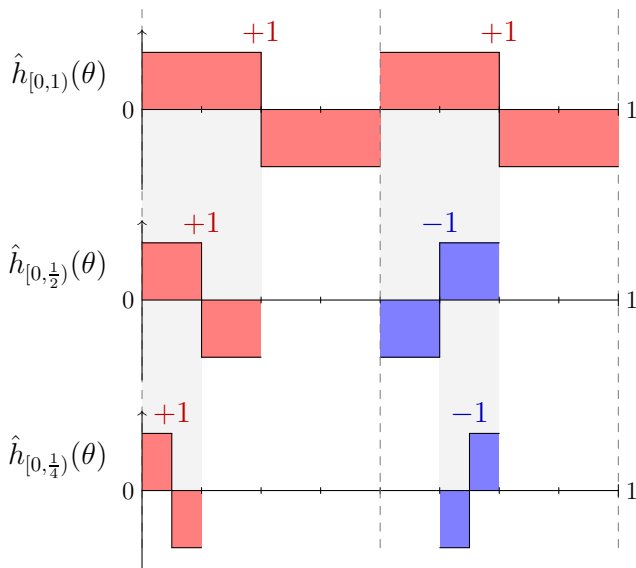
Proof: Diagonalization



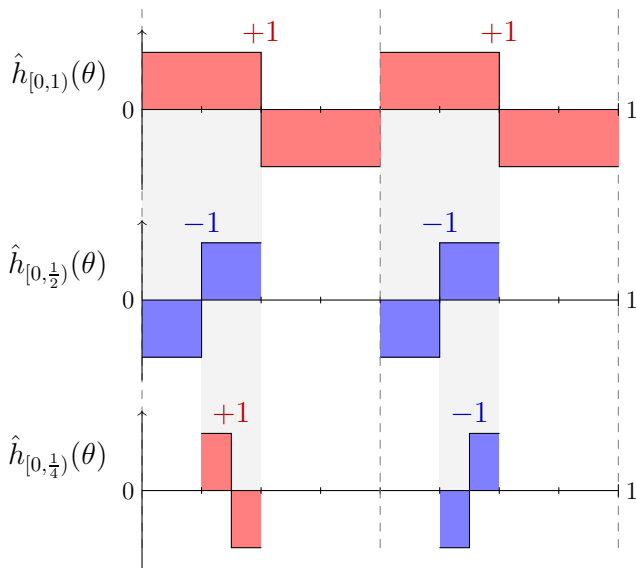
Proof: Diagonalization



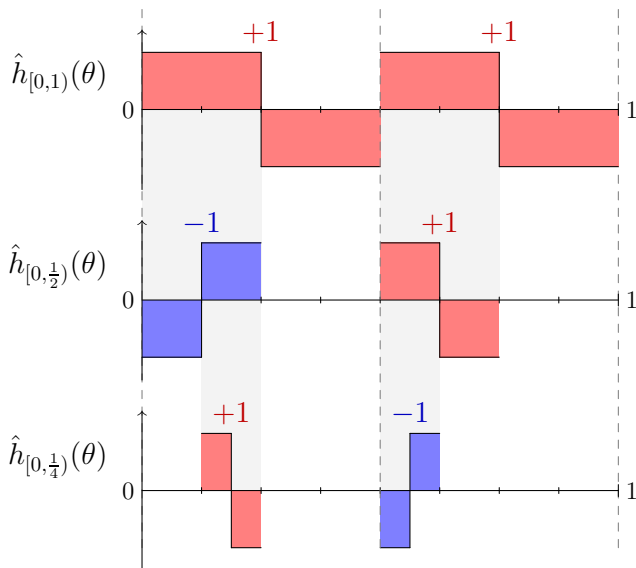
Proof: Diagonalization



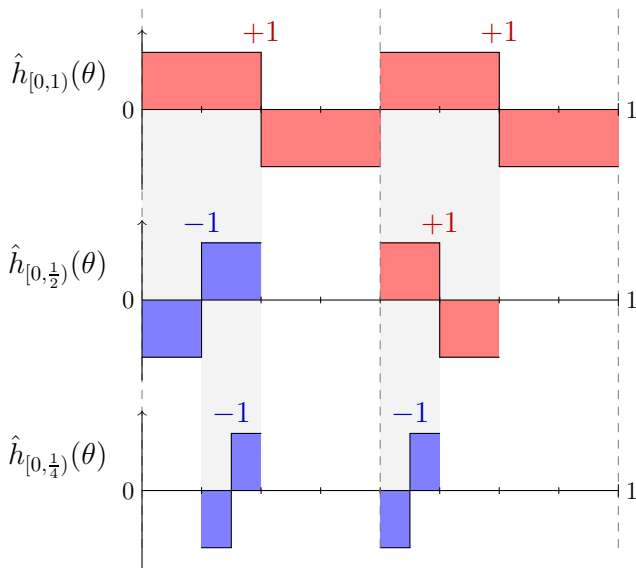
Proof: Diagonalization



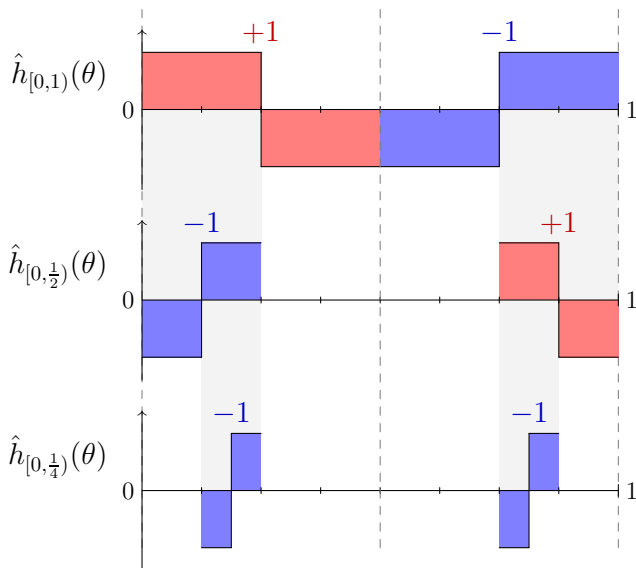
Proof: Diagonalization



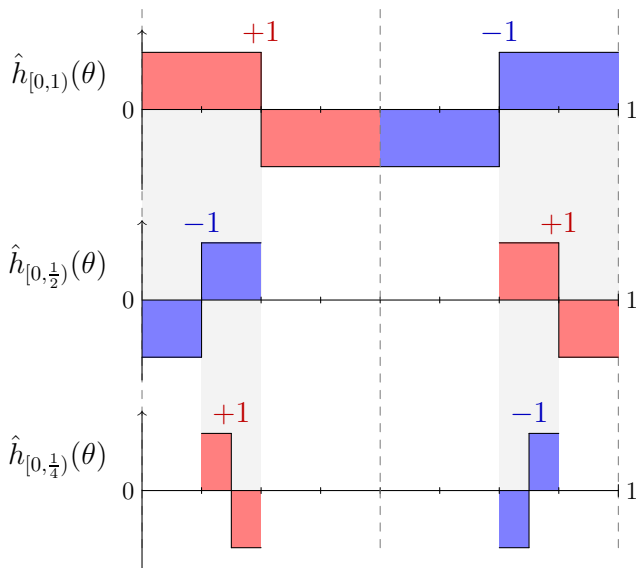
Proof: Diagonalization



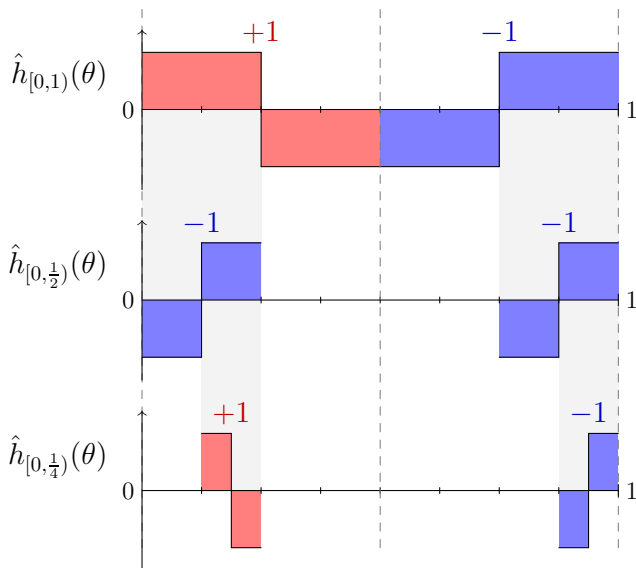
Proof: Diagonalization



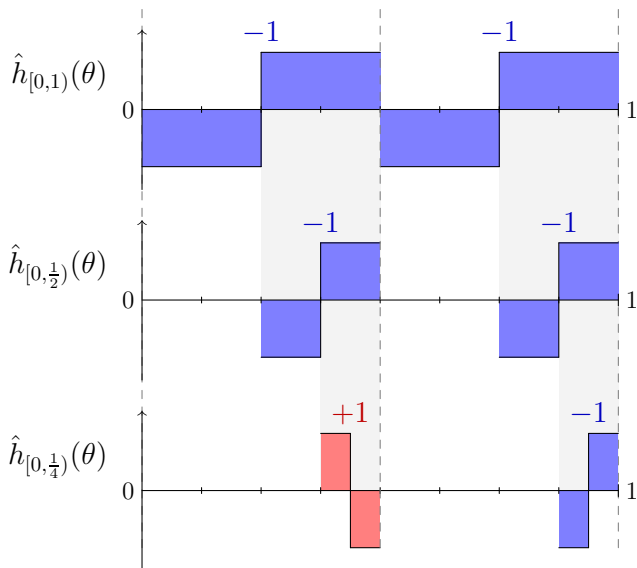
Proof: Diagonalization



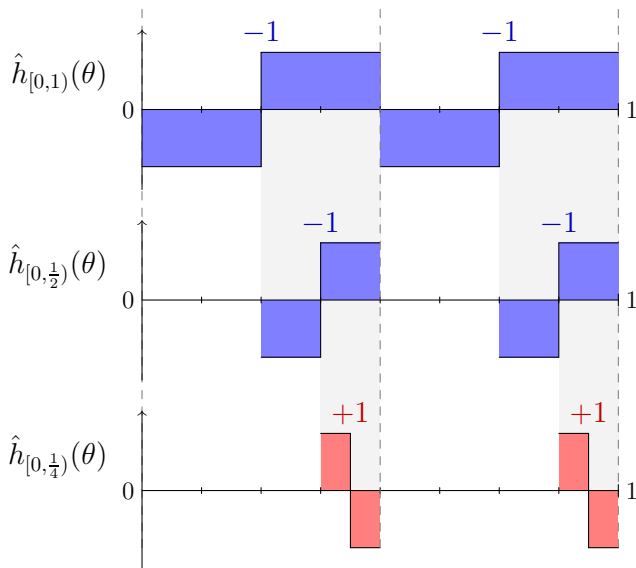
Proof: Diagonalization



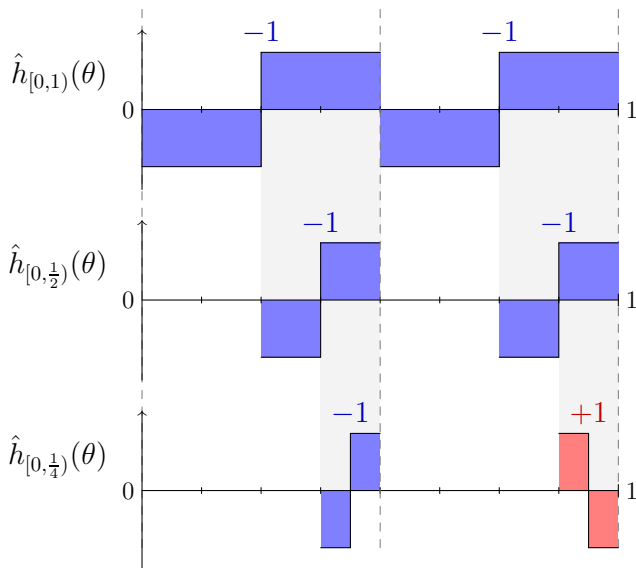
Proof: Diagonalization



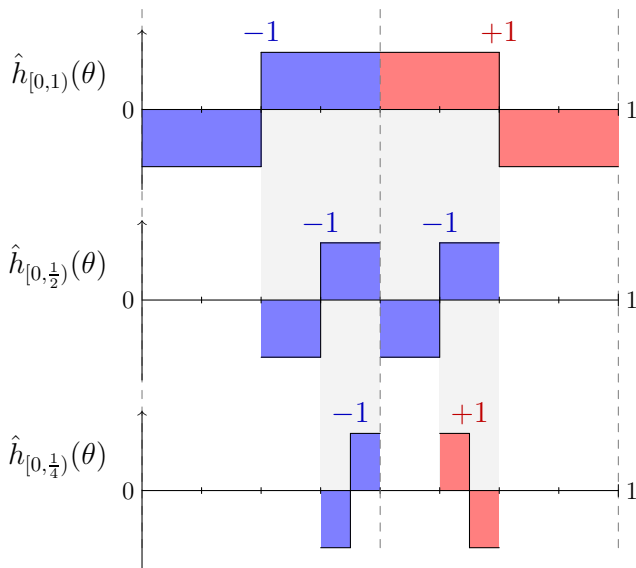
Proof: Diagonalization



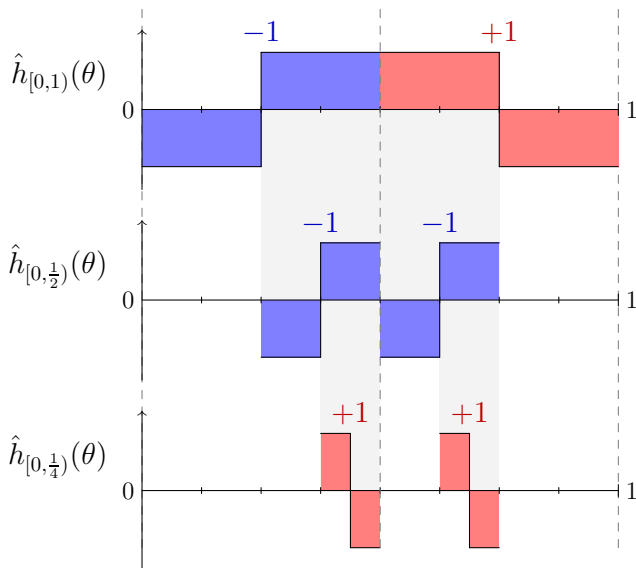
Proof: Diagonalization



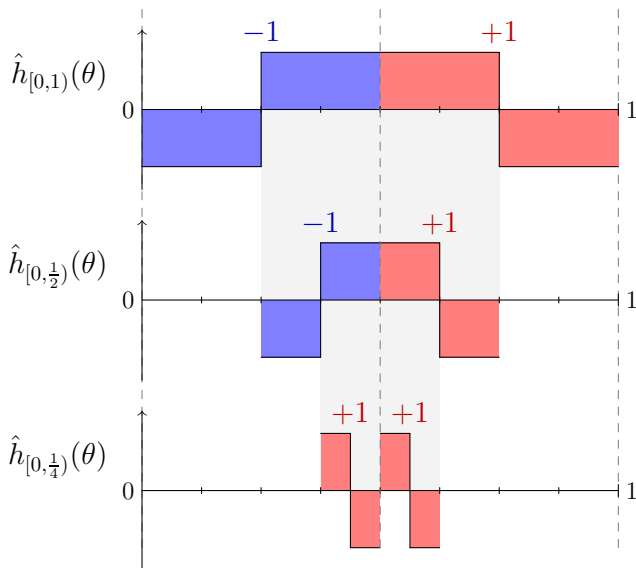
Proof: Diagonalization



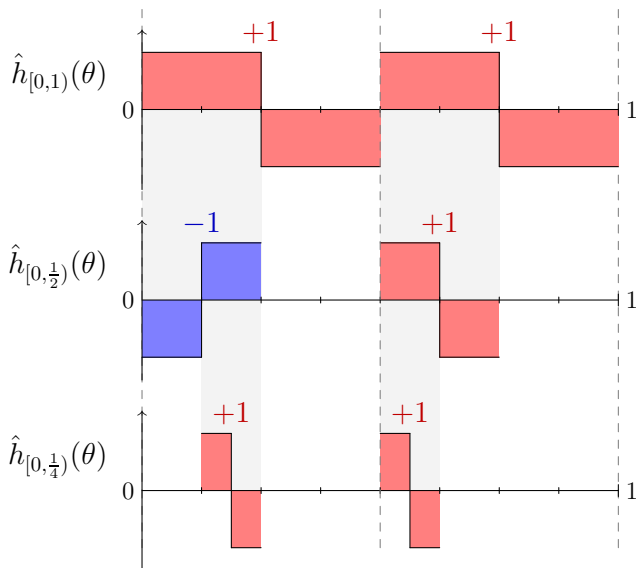
Proof: Diagonalization



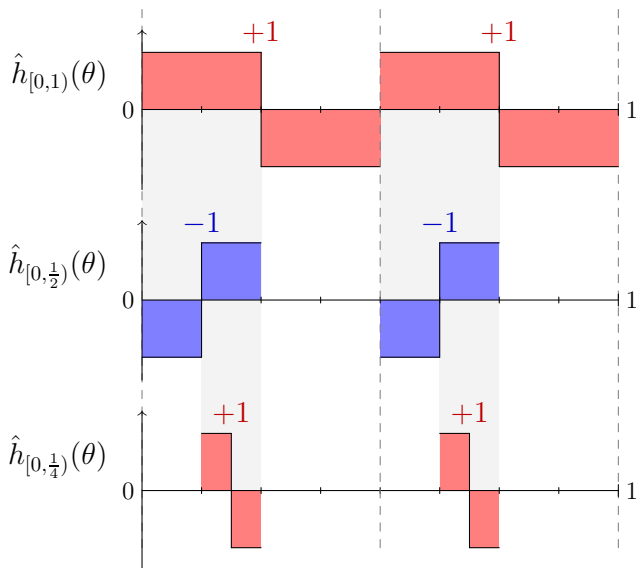
Proof: Diagonalization



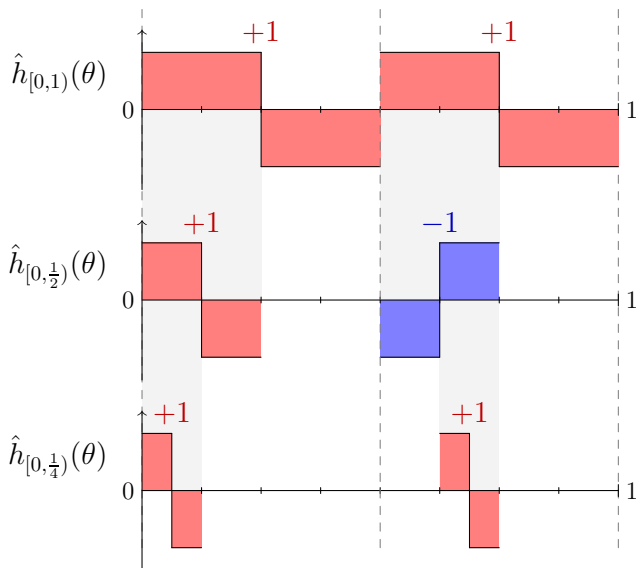
Proof: Diagonalization



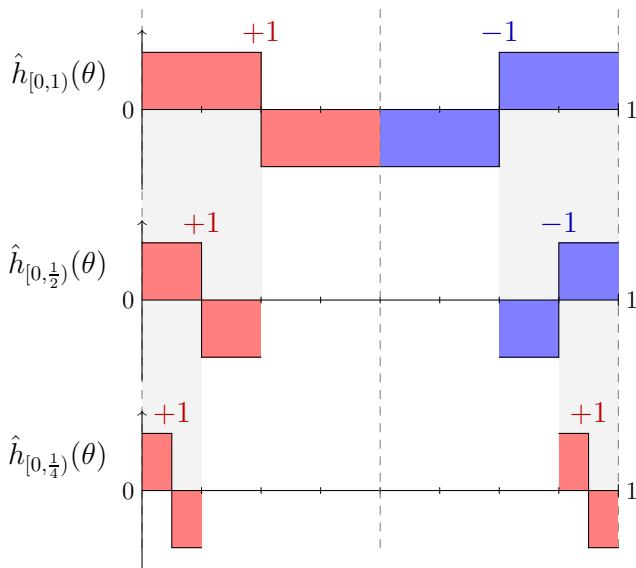
Proof: Diagonalization



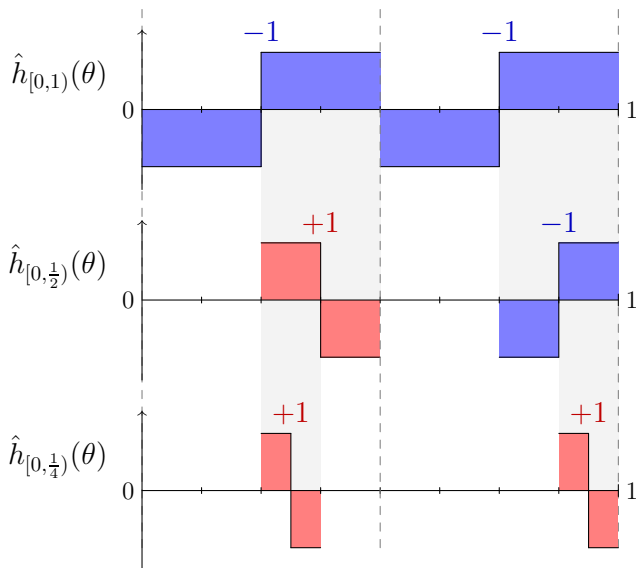
Proof: Diagonalization



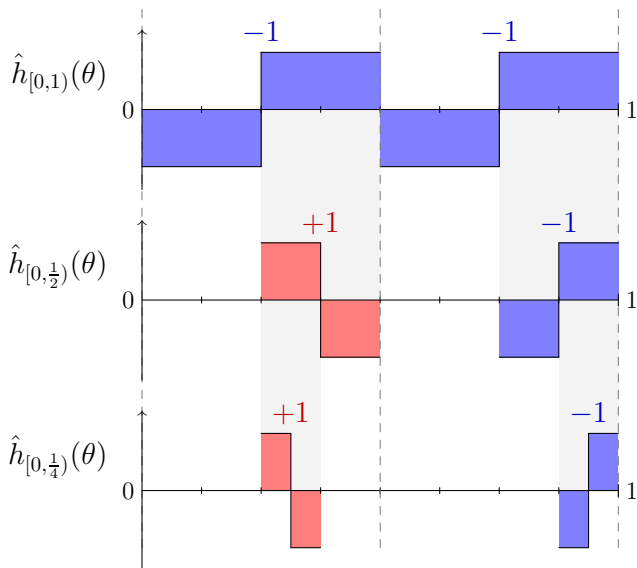
Proof: Diagonalization



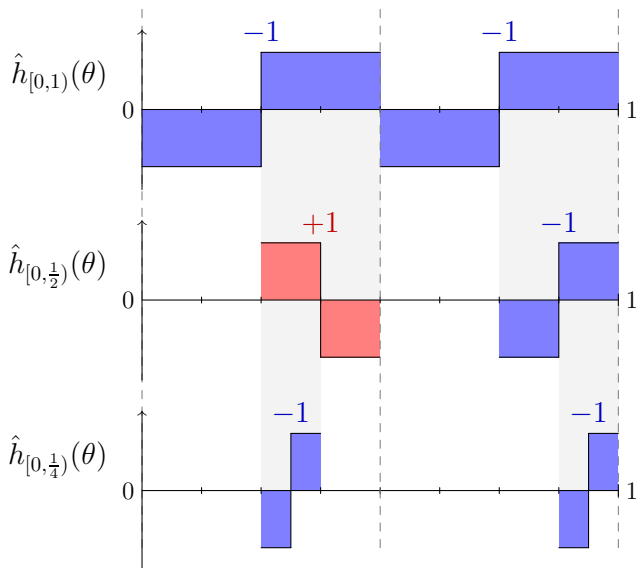
Proof: Diagonalization



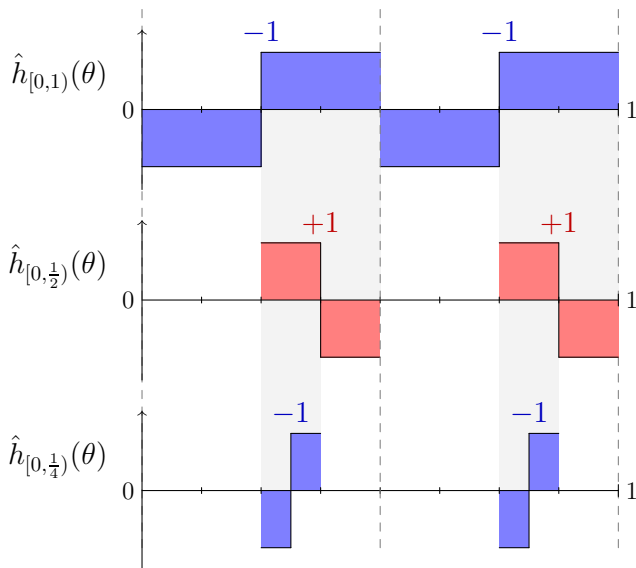
Proof: Diagonalization



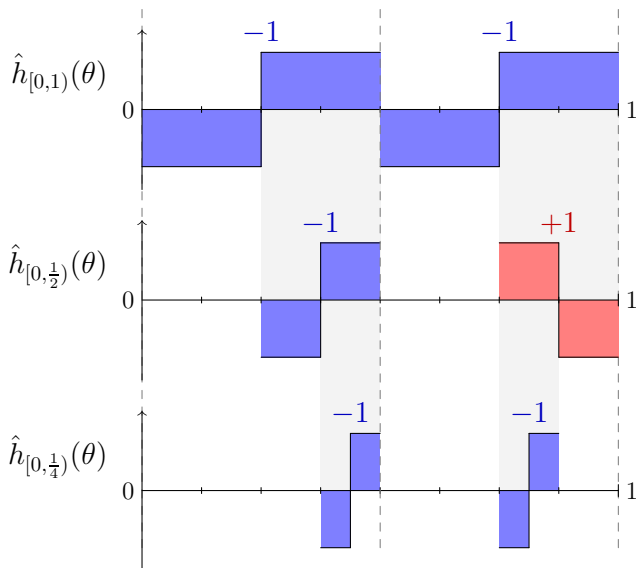
Proof: Diagonalization



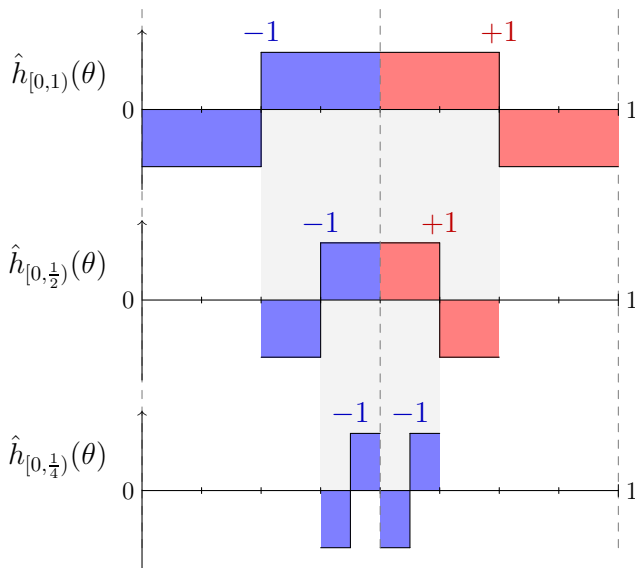
Proof: Diagonalization



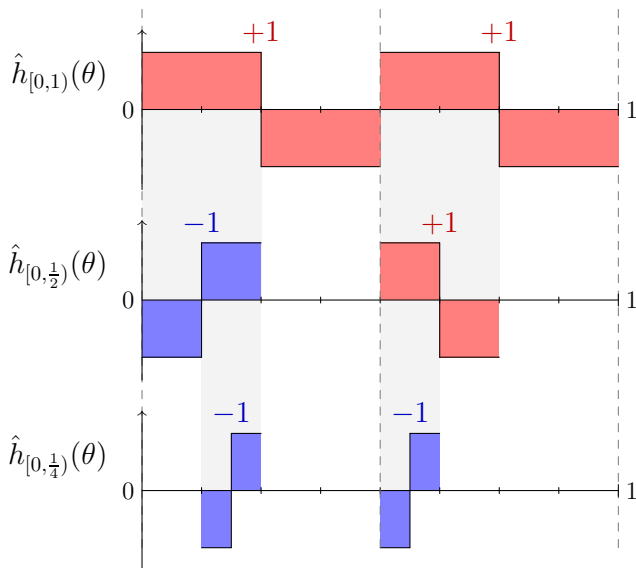
Proof: Diagonalization



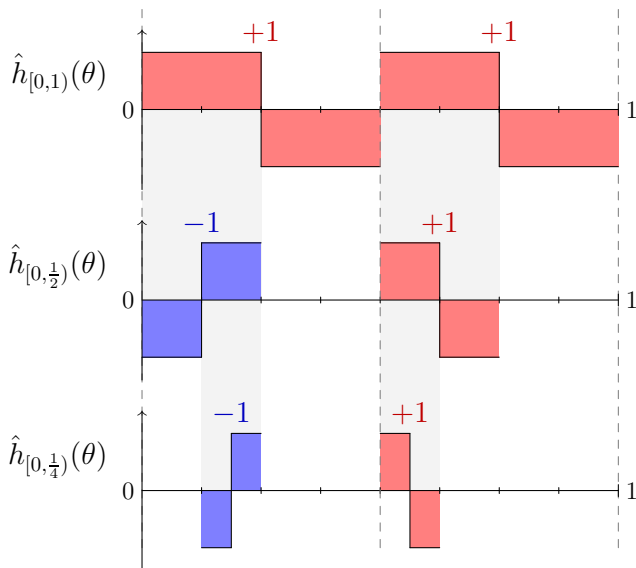
Proof: Diagonalization



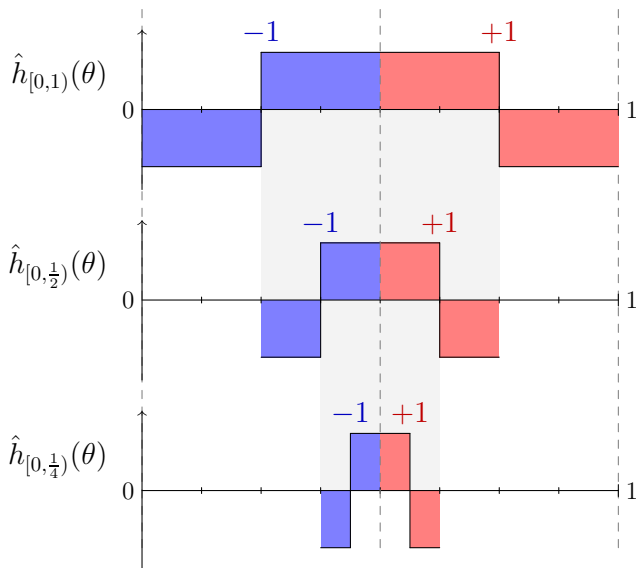
Proof: Diagonalization



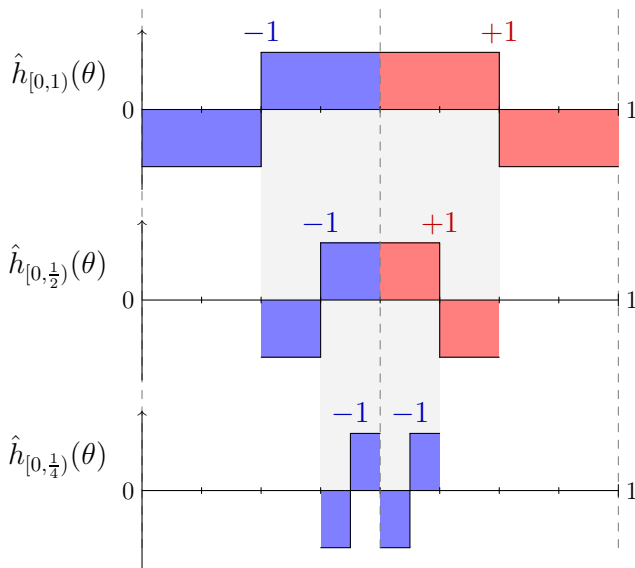
Proof: Diagonalization



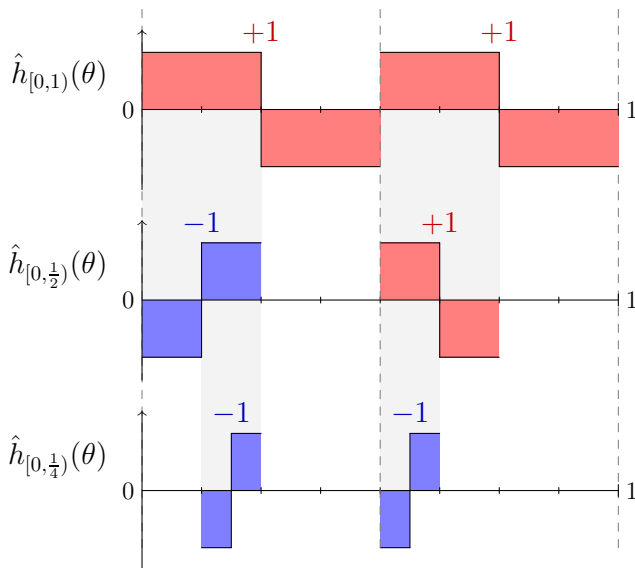
Proof: Diagonalization



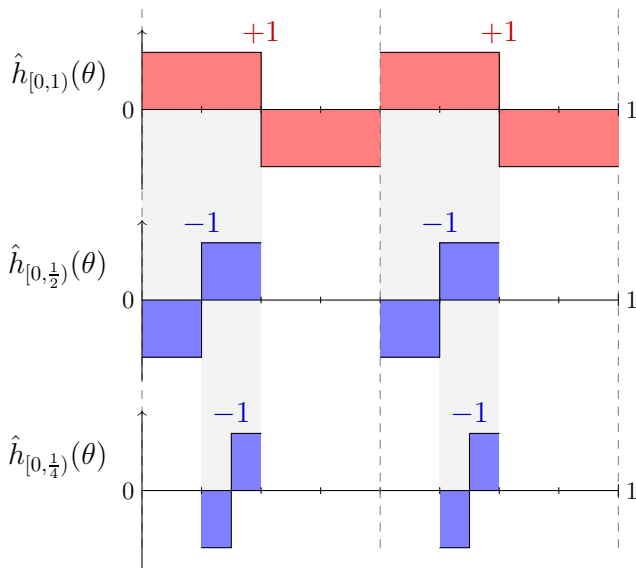
Proof: Diagonalization



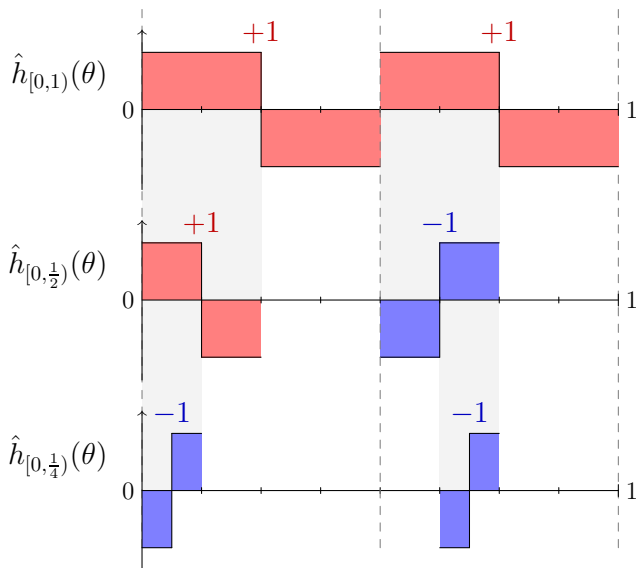
Proof: Diagonalization



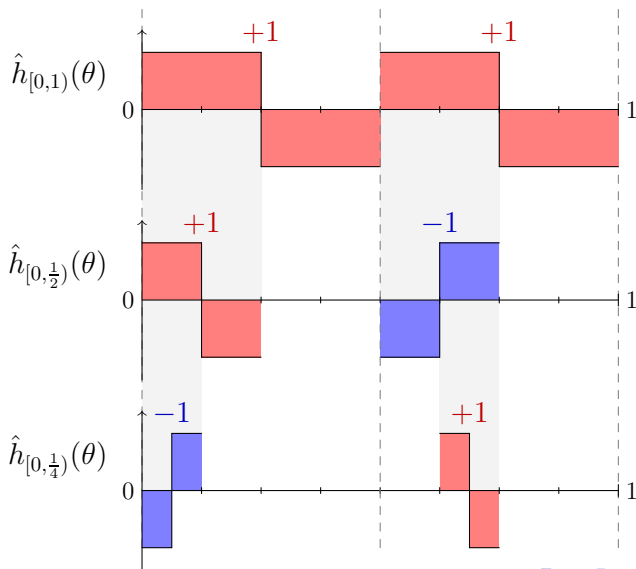
Proof: Diagonalization



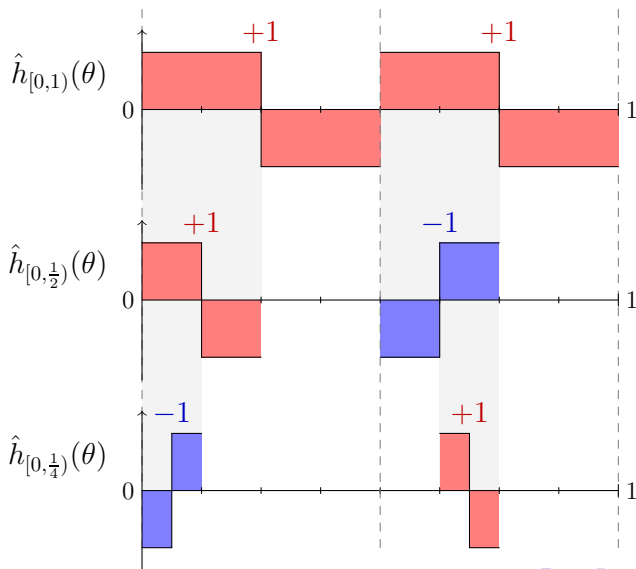
Proof: Diagonalization



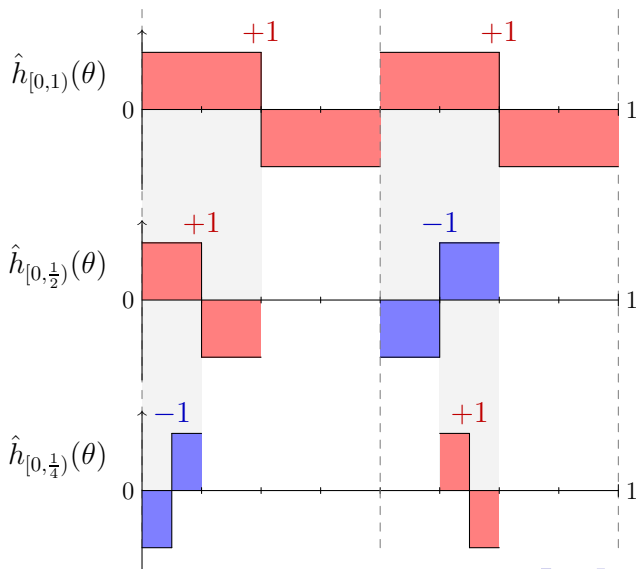
Proof: Diagonalization



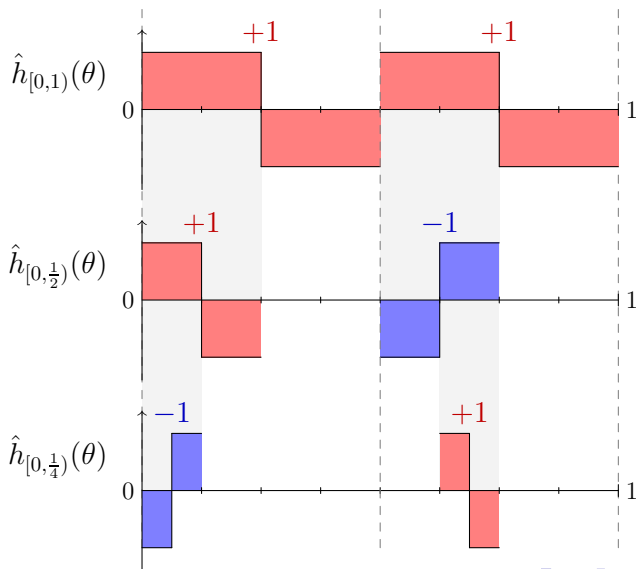
Proof: Diagonalization



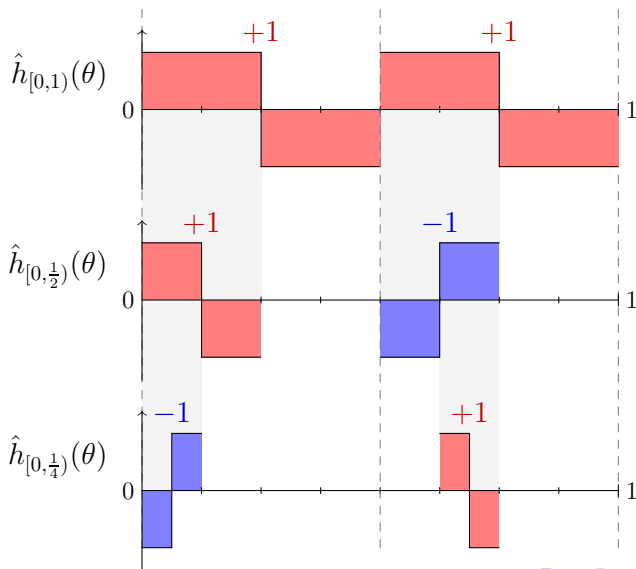
Proof: Diagonalization



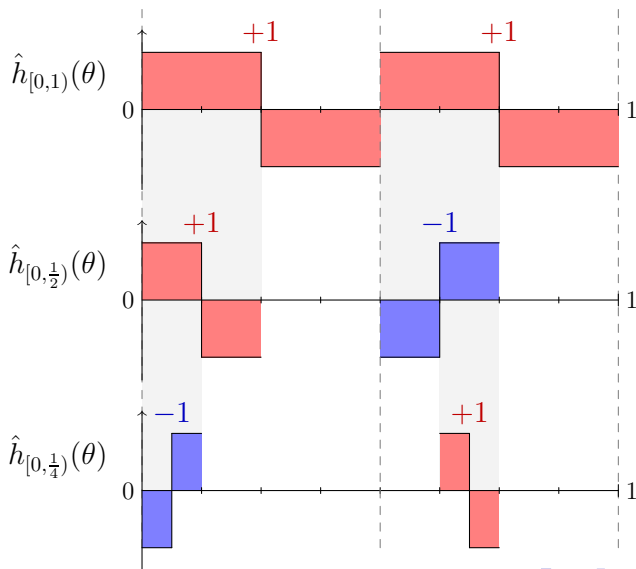
Proof: Diagonalization



Proof: Diagonalization



Proof: Diagonalization



Proof: Diagonalization and stabilization

- The random variables $X_{I,J}(\theta) = \langle \hat{h}_I(\theta), T\hat{h}_J(\theta) \rangle$ satisfy

$$\mathbb{E}X_{I,J} = 0 \text{ for } I \neq J \quad \text{and} \quad \mathbb{V}X_{I,J} \leq 3\|T\|^2 2^{-m/2}$$

(m = first level used in our construction)

- Choose m large \implies for some realization of θ , the system almost diagonalizes T .

Second step: *stabilization of Haar multipliers*

- Above, we obtain a Haar multiplier D with entries $(d_I)_I$.
- D is stable along every level: $d_I \approx d_J$ whenever $|I| = |J|$.
- Use pigeonhole principle to stabilize across all levels $\rightsquigarrow cI_{Y_n}$.

Proof: Diagonalization and stabilization

- The random variables $X_{I,J}(\theta) = \langle \hat{h}_I(\theta), T \hat{h}_J(\theta) \rangle$ satisfy

$$\mathbb{E}X_{I,J} = 0 \text{ for } I \neq J \quad \text{and} \quad \mathbb{V}X_{I,J} \leq 3\|T\|^2 2^{-m/2}$$

(m = first level used in our construction)

- Choose m large \implies for some realization of θ , the system almost diagonalizes T .

Second step: *stabilization of Haar multipliers*

- Above, we obtain a Haar multiplier D with entries $(d_I)_I$.
- D is stable along every level: $d_I \approx d_J$ whenever $|I| = |J|$.
- Use pigeonhole principle to stabilize across all levels $\rightsquigarrow cI_{Y_n}$.

Proof: Diagonalization and stabilization

- The random variables $X_{I,J}(\theta) = \langle \hat{h}_I(\theta), T \hat{h}_J(\theta) \rangle$ satisfy

$$\mathbb{E}X_{I,J} = 0 \text{ for } I \neq J \quad \text{and} \quad \mathbb{V}X_{I,J} \leq 3\|T\|^2 2^{-m/2}$$

(m = first level used in our construction)

- Choose m large \implies for some realization of θ , the system almost diagonalizes T .

Second step: *stabilization of Haar multipliers*

- Above, we obtain a Haar multiplier D with entries $(d_I)_I$.
- D is stable along every level: $d_I \approx d_J$ whenever $|I| = |J|$.
- Use pigeonhole principle to stabilize across all levels $\rightsquigarrow cI_{Y_n}$.

Proof: Diagonalization and stabilization

- The random variables $X_{I,J}(\theta) = \langle \hat{h}_I(\theta), T\hat{h}_J(\theta) \rangle$ satisfy

$$\mathbb{E}X_{I,J} = 0 \text{ for } I \neq J \quad \text{and} \quad \mathbb{V}X_{I,J} \leq 3\|T\|^2 2^{-m/2}$$

(m = first level used in our construction)

- Choose m large \implies for some realization of θ , the system almost diagonalizes T .

Second step: *stabilization of Haar multipliers*

- Above, we obtain a Haar multiplier D with entries $(d_I)_I$.
- D is stable along every level: $d_I \approx d_J$ whenever $|I| = |J|$.
- Use pigeonhole principle to stabilize across all levels $\rightsquigarrow cI_{Y_n}$.

Proof: Diagonalization and stabilization

- The random variables $X_{I,J}(\theta) = \langle \hat{h}_I(\theta), T\hat{h}_J(\theta) \rangle$ satisfy

$$\mathbb{E}X_{I,J} = 0 \text{ for } I \neq J \quad \text{and} \quad \mathbb{V}X_{I,J} \leq 3\|T\|^2 2^{-m/2}$$

(m = first level used in our construction)

- Choose m large \implies for some realization of θ , the system almost diagonalizes T .

Second step: *stabilization of Haar multipliers*

- Above, we obtain a Haar multiplier D with entries $(d_I)_I$.
- D is stable along every level: $d_I \approx d_J$ whenever $|I| = |J|$.
- Use pigeonhole principle to stabilize across all levels $\rightsquigarrow cI_{Y_n}$.

Proof: Diagonalization and stabilization

- The random variables $X_{I,J}(\theta) = \langle \hat{h}_I(\theta), T\hat{h}_J(\theta) \rangle$ satisfy

$$\mathbb{E}X_{I,J} = 0 \text{ for } I \neq J \quad \text{and} \quad \mathbb{V}X_{I,J} \leq 3\|T\|^2 2^{-m/2}$$

(m = first level used in our construction)

- Choose m large \implies for some realization of θ , the system almost diagonalizes T .

Second step: *stabilization of Haar multipliers*

- Above, we obtain a Haar multiplier D with entries $(d_I)_I$.
- D is stable along every level: $d_I \approx d_J$ whenever $|I| = |J|$.
- Use pigeonhole principle to stabilize across all levels $\rightsquigarrow cI_{Y_n}$.

Proof: Diagonalization and stabilization

- The random variables $X_{I,J}(\theta) = \langle \hat{h}_I(\theta), T\hat{h}_J(\theta) \rangle$ satisfy

$$\mathbb{E}X_{I,J} = 0 \text{ for } I \neq J \quad \text{and} \quad \mathbb{V}X_{I,J} \leq 3\|T\|^2 2^{-m/2}$$

(m = first level used in our construction)

- Choose m large \implies for some realization of θ , the system almost diagonalizes T .

Second step: *stabilization of Haar multipliers*

- Above, we obtain a Haar multiplier D with entries $(d_I)_I$.
- D is stable along every level: $d_I \approx d_J$ whenever $|I| = |J|$.
- Use pigeonhole principle to stabilize across all levels $\rightsquigarrow cI_{Y_n}$.

Thank you for your attention!